



(Prediction explanation = Local model explanation)

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Skatteetaten, 29.10.2021





## **Prediction explanation – by example**

- Car insurance
  - Response *y*: The insured crashes
  - Features  $\mathbf{x} = (x_1, \dots, x_M)$ : Data about the insured, his/her car and crashing history
  - Predictive model f: Model trained to predict probability of crash:  $f(\mathbf{x}) \approx \Pr(\mathbf{y} = yes | \mathbf{x})$



- Prediction explanation
  - Why did a guy with features x\* get a predicted probability of crashing equal to f(x\*)= 0.3?



## **Shapley values**

- Concept from (cooperative) game theory in the 1950s
- ► Used to distribute the total payoff to the players
- Explicit formula for the "fair" payment to every player *j*:  $\phi_j = \sum_{S \subseteq M \setminus \{j\}} \frac{|S|! (|M| - |S| - 1)}{|M|!} (v(S \cup \{j\}) - v(S))$  w(S) is the payoff with only players

v(S) is the payoff with only players in subset S

Several mathematical optimality properties



## Intuition behind the Shapley formula

Game with 3 players



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#### Shapley values for taxi sharing $v(\{R, B, G\}) = 60 + 40 + 100 = 200kr$ 140kr $v(\{\}) = 0$ 60kr $v(\{R\}) = 140kr$ $v(\{B\}) = 60 + 40 = 100kr$ 100k $v(\{G\}) = 60kr$ $v(\{R, B\}) = 60 + 40 + 100 = 200kr$ 40kr $v(\{R,G\}) = 60 + 40 + 100 = 200kr$ $v(\{B, G\}) = 60 + 40 = 100kr$

$$\phi_{R} = \frac{1}{3} \left( v(\{R, B, G\}) - v(\{B, G\}) \right) + \frac{1}{6} \left( v(\{R, B\}) - v(\{B\}) \right) + \frac{1}{6} \left( v(\{R, G\}) - v(\{G\}) \right) + \frac{1}{3} \left( v(\{R\}) - v(\{\}) \right) = 120 \text{ kr}$$
  

$$\phi_{B} = \frac{1}{3} \left( v(\{R, B, G\}) - v(\{R, G\}) \right) + \frac{1}{6} \left( v(\{R, B\}) - v(\{R\}) \right) + \frac{1}{6} \left( v(\{B, G\}) - v(\{G\}) \right) + \frac{1}{3} \left( v(\{B\}) - v(\{\}) \right) = 50 \text{ kr}$$
  

$$\phi_{G} = \frac{1}{3} \left( v(\{R, B, G\}) - v(\{R, B\}) \right) + \frac{1}{6} \left( v(\{R, G\}) - v(\{R\}) \right) + \frac{1}{6} \left( v(\{R, G\}) - v(\{B\}) \right) + \frac{1}{3} \left( v(\{G\}) - v(\{\}) \right) = 30 \text{ kr}$$

## Shapley values for prediction explanation

- Approach popularised by Lundberg & Lee (2017)
  - Players = features  $(x_1, ..., x_M)$
  - Payoff = prediction  $(f(\mathbf{x}^*))$
  - Contribution function:  $v(S) = E[f(\mathbf{x})|\mathbf{x}_S = \mathbf{x}_S^*]$
  - Properties

$$\sum_{j=1}^{M} \phi_j = f(\mathbf{x}^*) - \phi_0$$

$$f(\mathbf{x}) \coprod x_j$$
  $x_i, x_j$  same contribution  
implies  $\phi_j = 0$  implies  $\phi_i = \phi_j$ 

► Rough interpretation of  $\phi_j$ : The prediction change when you don't know the value of  $x_j$  – averaged over all features



## **Example of Shapley value explanation**

- Consider a model f(x) trained to predict the price of a car insurance based on the following features x:
  - Owner's age, owner's gender, type of car, time since the car was registered, number of accidents the last 5 years



Shapley value prediction explanation



## Linear models $f(x) = \beta_0 + \sum_{j=1} \beta_j x_j$

Linear model with independent covariates:

 $\phi_j = \beta_j (x_j^* - E[x_j]), \quad \phi_0 = \beta_0 + \sum_j \beta_j E[x_j]$ 

- Explanation not simple with dependent covariates!
  - Example
    - $x_1 = \text{height (cm)}$
    - $x_2 = \text{weight (kg)}$
    - Y = PB in high jump (cm)
  - Model 1:  $Y = 100 + 2x_1 2x_2$
  - Model 2:  $Y = 100 2x_1 + 2x_2$





- Consider f(x) trained to predict housing prices in Boston based on 16 features x, including
  - LSTAT % lower status of the population
  - RM average number of rooms per dwelling
  - NOX nitric oxides concentration (parts per 10 million)
  - RAD index of accessibility to radial highways
  - TAX full-value property-tax rate per \$10,000
  - CRIM per capita crime rate by town
- Next slides shows visualizations from the shap Python package



f(x) = 24.019







## Two challenges with Shapley values for prediction explanation

1. The exponentially growing computational complexity in the Shapley formula  $\phi_j = \sum_{S \subseteq M \setminus \{j\}} \frac{|S|! (|M| - |S| - 1)}{|M|!} (v(S \cup \{j\}) - v(S))$ 

 Approximate solutions may be obtained by cleverly reducing the sum by subset sampling (KernelSHAP; Lundberg & Lee, 2017)

2. Estimating the contribution function

$$v(S) = E[f(\mathbf{x})|\mathbf{x}_S = \mathbf{x}_S^*] = \int f(\mathbf{x}_{\bar{S}}, \mathbf{x}_S) p(\mathbf{x}_{\bar{S}}|\mathbf{x}_S = \mathbf{x}_S^*) \mathrm{d}\mathbf{x}_{\bar{S}}$$

Lundberg & Lee (2017), Python shap package, uses the approximation  
$$v(S) \approx \int f(x_{\bar{S}}, x_{\bar{S}}^*) p(x_{\bar{S}}) dx_{\bar{S}}$$

This implicitly assumes the features are **independent**!

### **Consequences of the independence assumption**

- Requires evaluating  $f(x_{\bar{s}}, x_{s})$  at potentially <u>unlikely or illegal</u> combinations of  $x_{\bar{s}}$  and  $x_{s}$ 
  - Example 1
    - Number of transactions to Switzerland: 0
    - Average transaction amount to Switzerland: 100 €

- ► Example 2
  - Age: **17**
  - Marital status: Widow
  - Profession: Professor





## **NR/Big Insight work on Shapley values**

<u>Dependence-aware</u> approaches to estimate

 $v(S) = E[f(\mathbf{x})|\mathbf{x}_S = \mathbf{x}_S^*]$  properly

- We do this by estimating  $p(x_{\bar{S}}|x_{\bar{S}} = x_{\bar{S}}^*)$  properly
- Several alternative methods
  - Gaussian distribution
  - Empirical nonparametric method
  - Empirical margins + vine copulas to estimate dependence structure
  - Conditional inference trees (ctree)
  - Variational autoencoders with arbitrary conditioning (VAEAC)
  - Methods implemented in the shapr R-package





## Nice to know

- Independence approach (most common)
  - There are different "explainers" in the **shap** Python package
    - General purpose, tree based models, deep learning, NLP
  - If you are using Shapley values produced directly by the GBM libraries xgboost, lightgbm, catboost, you are using the tree based approach in shap
  - Independence vs dependence-aware approaches in practice
    - Consider  $f(x_1, x_2) = x_1$ ,  $cor(x_1, x_2) = \rho \neq 0$
    - Independence approach will give  $\phi_2 = 0$
    - Dependence-aware approach will give  $\phi_2 \neq 0$
  - Dependence aware approaches
    - Comes at a higher computational cost
    - May give different results depending on what dependence-estimation method you use

## Nice to know II

- Be careful when using and interpreting Shapley values from the independence approach
  - May be useful for pure debugging/investigation of how  $f(\cdot)$  behaves
- Dependence-aware approach should be used in practical applications, as explanations of individual predictions (where feature dependence needs to be obeyed)

Some authors have claimed the independence approach is the right one referring to causal inference, but this has recently been rejected by a more general causal inference perspective (Heskes et al., 2020)



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